

Lecture 3: rigid body dynamics

- *kinematics example: rolling no slip*
- *rotational equation of motion*
- *mass moment of inertia*
- *solving rigid body dynamics problems*
- *dynamics example: pulley with mass*

Rigid Body Kinematics

$$v_A = v_B + (\omega \times r_{A/B})$$

$$a_A = a_B + (\alpha \times r_{A/B}) + (\omega \times (\omega \times r_{A/B}))$$

- Useful Shortcuts for 2D planar motion $\alpha = \alpha \mathbf{k}$
 $\omega = \omega \mathbf{k}$
 $\mathbf{r} = r_x \mathbf{i} + r_y \mathbf{j}$

$$\omega \times r = -r_y \omega \mathbf{i} + r_x \omega \mathbf{j}$$

$$\alpha \times r = -r_y \alpha \mathbf{i} + r_x \alpha \mathbf{j}$$

$$\omega \times (\omega \times r) = -r_x \omega^2 \mathbf{i} - r_y \omega^2 \mathbf{j}$$

Rigid Body Dynamics

Linear Motion:

$$\mathbf{F} = m\mathbf{a} = \frac{d(m\mathbf{v})}{dt}$$

sum of the forces is the time rate of change of linear momentum

Works for particles - and also works for rigid bodies if the acceleration is at the center of mass!

$$\mathbf{F} = m\mathbf{a}_G$$

Rigid Body Dynamics

Rotational Motion:

$$\mathbf{M}_G = \frac{d(\mathbf{H}_G)}{dt} = \dot{\mathbf{H}}_G$$

about the center of mass

sum of the moments is
the time rate of change
of angular momentum

Rigid Body Dynamics

Rotational Motion:

$$\mathbf{M}_G = \frac{d(\mathbf{H}_G)}{dt} = I_G \alpha$$

sum of the moments is
the time rate of change
of angular momentum

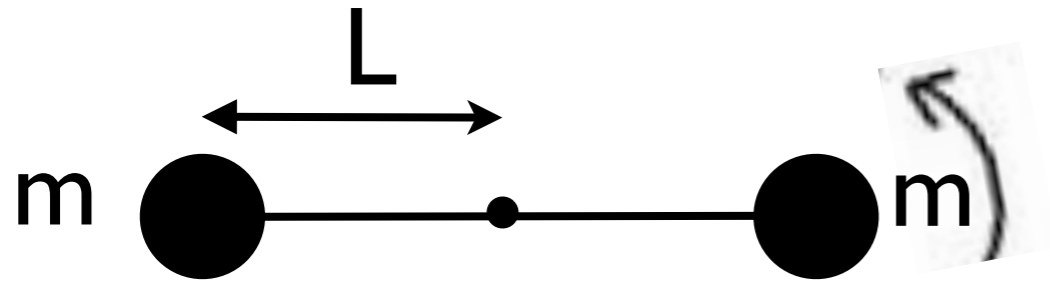
Mass Moment of Inertia:

$$I_G = \sum_i (m_i r_i^2) = \int_V (\rho r^2) dV$$

“Rotational Inertia”

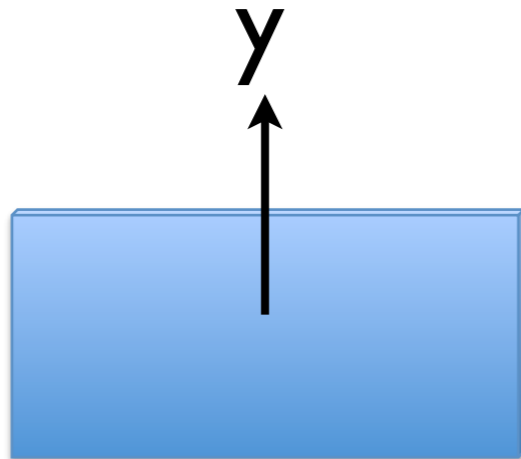
Resistance to angular acceleration

Mass Moment of Inertia

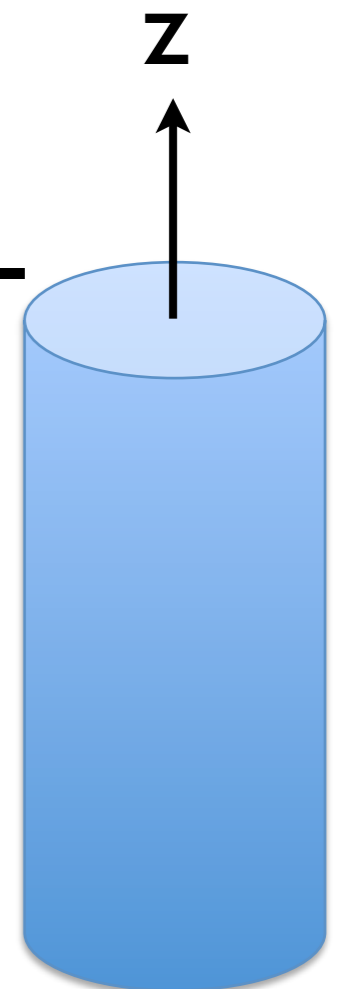


Two spherical masses connected by a massless bar

thin plate, height b , length c , rotating around y -axis

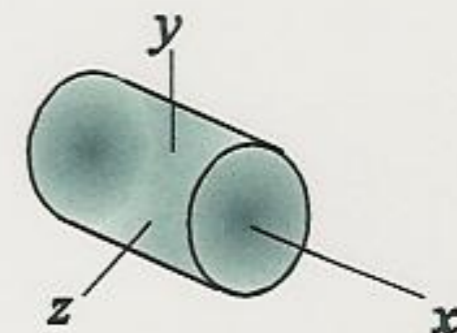
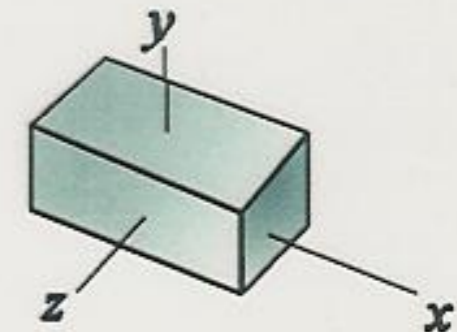
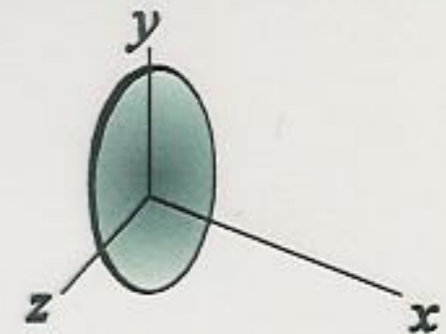
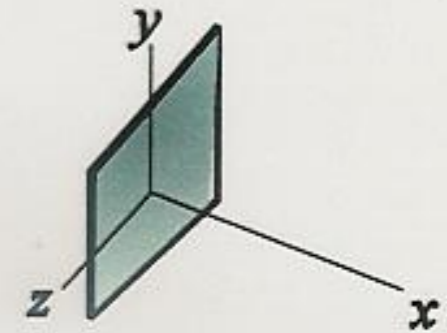
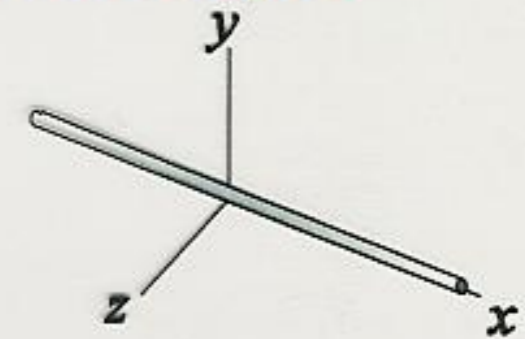


solid cylinder length L radius R , rotating around z -axis

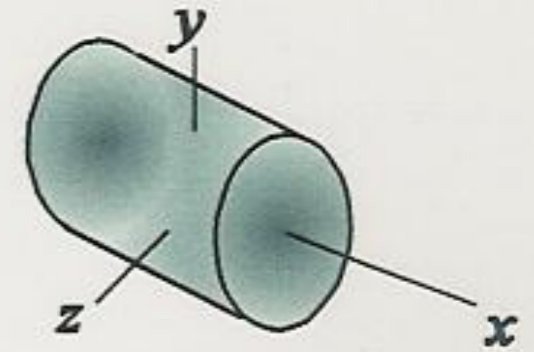


Principal Mass Moments of Inertia of Solid Geometrical Shapes

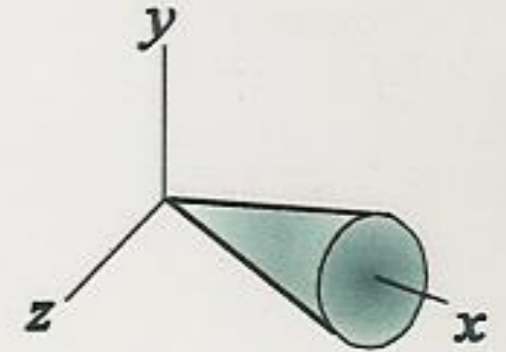
	I_x	I_y	I_z
Slender Rod <i>m</i> = mass, <i>l</i> = length of rod	0	$1/12 ml^2$	$1/12 ml^2$
Rectangular Plate <i>m</i> = mass, <i>b</i> = height of plate, <i>c</i> = width of plate	$1/12 m(b^2+c^2)$	$1/12 mc^2$	$1/12 mb^2$
Thin Disk <i>m</i> = mass, <i>r</i> = radius of disk	$1/2 mr^2$	$1/4 mr^2$	$1/4 mr^2$
Rectangular Prism <i>m</i> = mass, <i>a</i> = depth (<i>x</i>), <i>b</i> = height (<i>y</i>), <i>c</i> = width (<i>z</i>)	$1/12 m(b^2+c^2)$	$1/12 m(a^2+c^2)$	$1/12 m(a^2+b^2)$
Circular Cylinder <i>m</i> = mass, <i>l</i> = length of cylinder, <i>r</i> = radius	$1/2 mr^2$	$1/12 m(3r^2+l^2)$	$1/12 m(3r^2+l^2)$



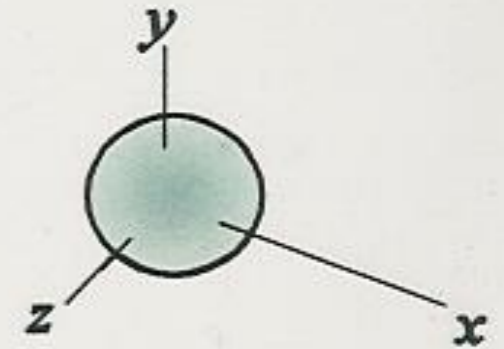
Elliptical Cylinder $\frac{1}{12} m(3c^2 + l^2)$ $\frac{1}{12} m(3b^2 + l^2)$ $\frac{1}{4} m(b^2 + c^2)$
 $m = \text{mass}, l = \text{length of cylinder (x)}, b = \text{height/2 (y)}, c = \text{width/2 (z)}$



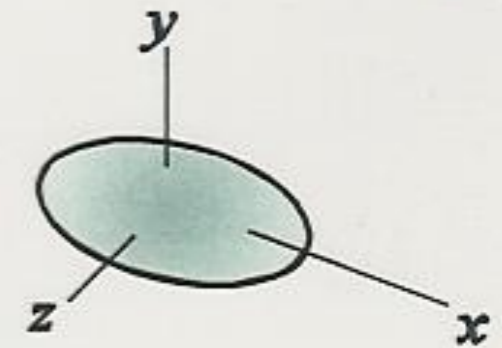
Circular Cone $\frac{3}{10} mr^2$ $\frac{3}{5} m(\frac{1}{4} r^2 + l^2)$ $\frac{3}{5} m(\frac{1}{4} r^2 + l^2)$
 $m = \text{mass}, l = \text{length of cone}, r = \text{radius at base}$



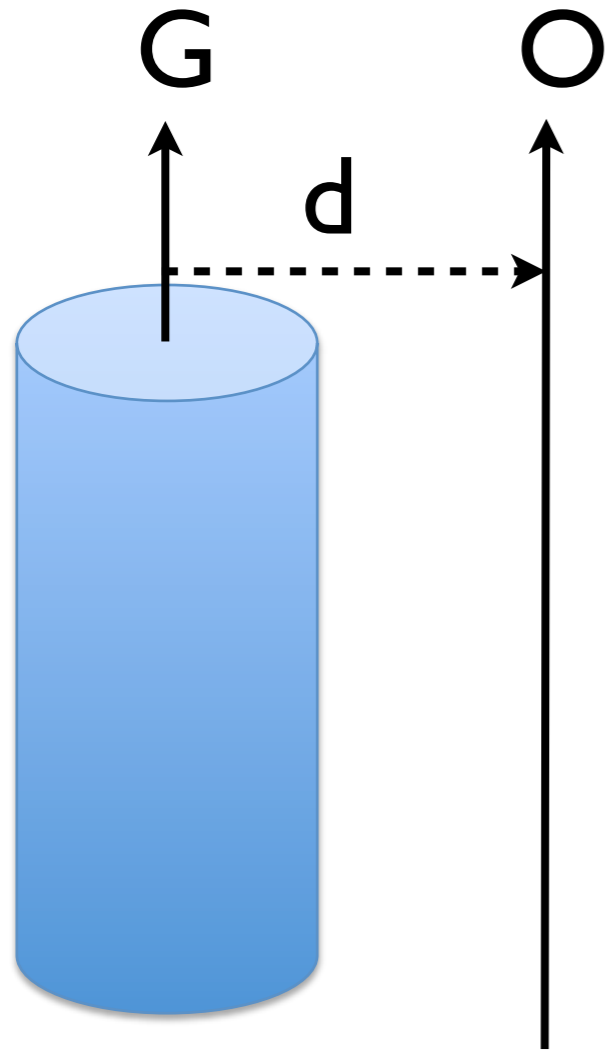
Sphere $\frac{2}{5} mr^2$ $\frac{2}{5} mr^2$ $\frac{2}{5} mr^2$
 $m = \text{mass}, r = \text{radius}$



Ellipsoid $\frac{1}{5} m(b^2 + c^2)$ $\frac{1}{5} m(a^2 + c^2)$ $\frac{1}{5} m(a^2 + b^2)$
 $m = \text{mass}, a = \text{depth (x)}, b = \text{height (y)}, c = \text{width (z)}$



Parallel Axis Theorem



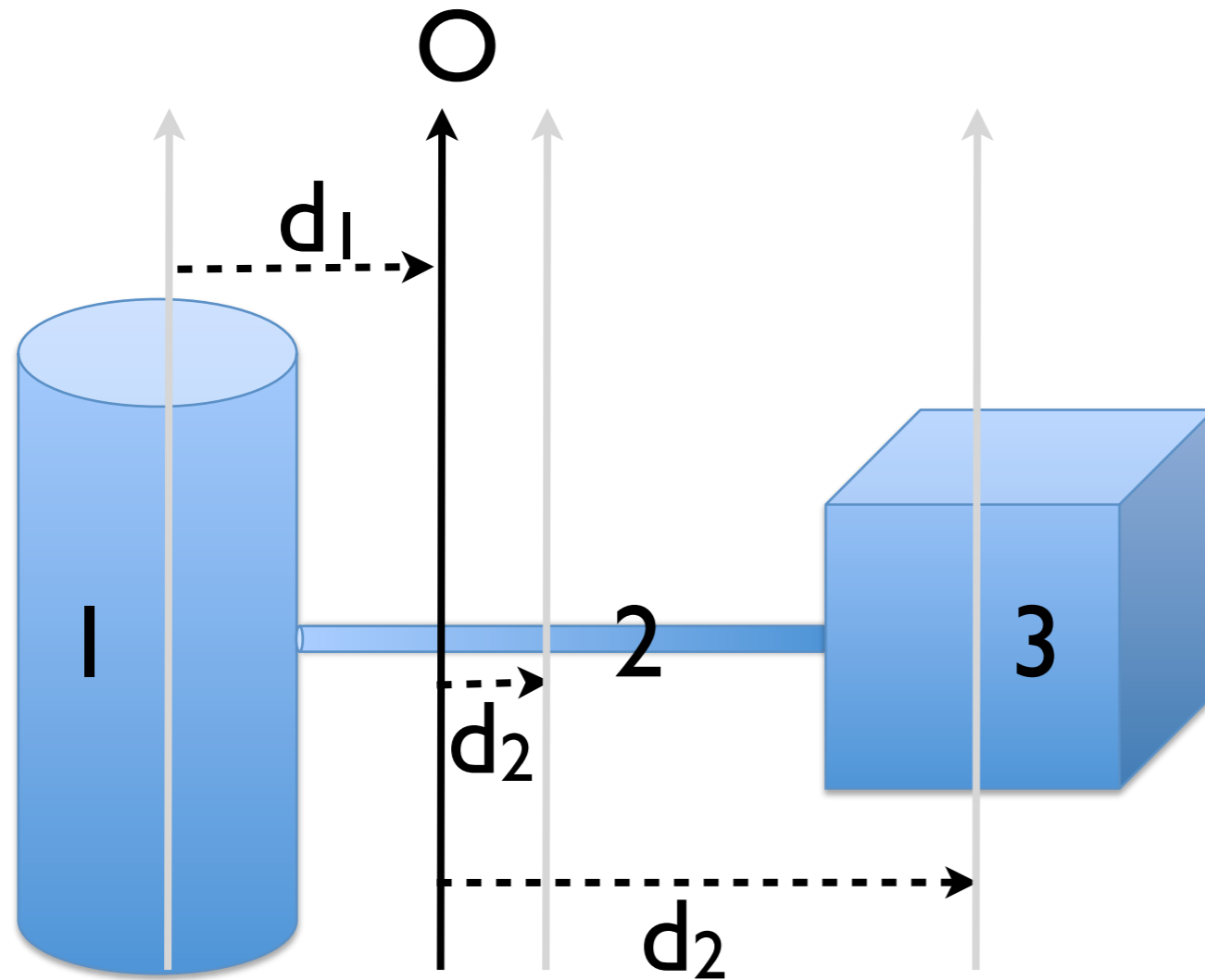
object rotating around axis
“O” NOT through the CG

Find parallel axis through CG

$$I_O = I_G + md^2$$

I_G can read from tables

Composite Bodies



$$I_O = I_{G1} + m_1 d_1^2 + I_{G2} + m_2 d_2^2 + I_{G3} + m_3 d_3^2$$

I_G can read from tables

rigid body dynamics problems: 2D planar motion

- *Free Body Diagram!*
- *3 equations of motion:*

$$F_x = ma_x$$

$$F_y = ma_y$$

- *problem constraints* $M_z = I\alpha$
- *mass moment of inertia calculation*
- *can we solve? if not, need more eqns:*
- *kinematics equations: connection between*

α, ω AND v, a

3. Analysis of Car Crash

A 2500 kg car crashes into a fixed barrier wall at speed $v_c=5$ m/s and is observed to rebound with a velocity of $v_f=2$ m/s. The total impact time is 0.5s. The passenger's torso and head is treated as a single rigid body, rotating about the point O as shown in the diagram below, where L is the distance from O to the center of mass.

$I_G=1.2mL^2$ for the passenger.

refer to 2012 HW#7 for more details and solution

